## Absorbing boundary conditions for Schrödinger Equations

by

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# INTRODUCTION

**2** One dimensional Schrödinger Eq.

Two dimensional Schrödinger Eq. with potential

EXTENSION TO 2D NONLINEAR EQUATION



# INTRODUCTION

**2** One dimensional Schrödinger Eq.

**3** Two dimensional Schrödinger Eq. with potential

**EXTENSION TO 2D NONLINEAR EQUATION** 



## MOTIVATION

## THE SCHRÖDINGER EQ. IN $\mathbb{R}^d$

(S) 
$$\begin{cases} i\partial_t u + \Delta u + \mathscr{V}(x, t, u) \, u = 0, & (x, t) \in \mathbb{R}^d \times \mathbb{R}^+ \\ u(x, 0) = u_0(x), & x \in \mathbb{R}^d \end{cases}$$

- u(x,t) : complex wave function
- $\mathscr V$  potential and/or nonlinearity :  $\mathscr V = V(x,t) + f(|u|)u$
- $u_0$  compact support in  $\Omega$



- Truncation  $\mathbb{R} \times [0;T] \longrightarrow \Omega_T := ]x_l, x_r[\times[0;T]]$
- Introduction of a fictitious boundary  $\Sigma := \partial \Omega = \{x_l, x_r\}$
- The boundary condition on  $x_l$  must represent the effect of the potential on  $]-\infty, x_l]$ .

# MOTIVATION

What happens when one does not take care of BCs?

0.4

0.2

0

x

Potential V(x) = x

Initial datum : gaussian  $u_0(x) = e^{-x^2 + 10ix}$ Homogeneous Dirichlet BCs :  $u|_{\Sigma} = 0$ .



10



0.2

0.1

15

# MOTIVATION

What happens when one does not take care of BCs?

Potential V(x) = x

Initial datum : gaussian  $u_0(x) = e^{-x^2 + 10ix}$ Homogeneous Dirichlet BCs :  $u|_{\Sigma} = 0$ .



 $\Rightarrow$  Parasistic reflexions

## DERIVATION OF BCs



### DERIVATION OF BCs



GOAL : to derive artificial boundary conditions in order to approximate the exact solution u of (S), restricted to  $\Omega_T.$ 

- absorbing boundary conditions (ABC) : well posed problem + "energy functional " absorbed at the boundary
- transparent boundary conditions (TBC) : approximate solution coincides with u on  $\Omega_T.$
- ABC : local in space and/or in time
- TBC : non local in space and time

#### Which formulation for the BC?

• The boundary condition is formulated with the Dirichlet-to-Neumann map :

 $\partial_{\mathbf{n}} u + i \Lambda^+ u = 0, \quad \text{on } \Sigma_T$ 

• Interesting in a variational formulation for a finite element method.

$$\int_{\Omega} \Delta u \psi \, d\omega \longrightarrow - \int_{\Omega} \nabla u \cdot \nabla \psi \, d\omega + \int_{\Sigma} \partial_{\mathbf{n}} u \psi \, d\sigma.$$

•  $\Lambda^+$  brings into play fractional operators

#### FRACTIONAL OPERATORS

$$\begin{split} \partial_t^{1/2} f(t) &= \frac{1}{\sqrt{\pi}} \partial_t \int_0^t \frac{f(s)}{\sqrt{t-s}} ds, \\ I_t^{\alpha/2} f(t) &= \frac{1}{\Gamma(\alpha/2)} \int_0^t (t-s)^{\alpha/2} f(s) \, ds, \end{split}$$

# INTRODUCTION

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## **EXTENSION TO 2D NONLINEAR EQUATION**



TBCs are non local w.r to t and connect  $\partial_x u(x_{l,r},t)$  with  $u(x_{l,r},t)$ .

DIRICHLET-TO-NEUMANN (DTN) MAP  $\partial_{\mathbf{n}} u(x,t) = -\frac{e^{-i\frac{\pi}{4}}}{\sqrt{\pi}} e^{-iV_{l,r}t} \frac{\partial}{\partial t} \int_{0}^{t} \frac{u(x,\tau)e^{iV_{l,r}\tau}}{\sqrt{t-\tau}} d\tau \quad \text{in } x = x_{l}, x_{r},$ 

where **n** denotes the outwardly unitary normal vector in  $x_l$ ,  $x_r$ .

NOTATIONS AND HYPOTHESIS :

- $\Omega = ]x_l, x_r[, \Omega_l = ] \infty, x_l], \Omega_r = [x_r, \infty[, \Gamma = \{x_l, x_r\}]$
- Continuity of u and  $\partial_x u$  through  $\Gamma$

### TBCs for linear S. in 1D

#### Interior problem

$$\begin{cases} (i\partial_t + \partial_x^2)v = 0, \ x \in \Omega, \ t > 0, \\ \partial_x v = \partial_x w, \ x \in \Gamma, \ t > 0, \\ v(x,0) = u^0(x), \ x \in \Omega. \end{cases}$$

#### Exterior problem

$$\begin{cases} (i\partial_t + \partial_x^2)w = 0, \ x \in \overline{\Omega}, t > 0, \\ w(x,t) = v(x,t), \ x = x_{l,r}, \ t > 0, \\ \lim_{|x| \to \infty} w(x,t) = 0, \ t > 0, \\ w(x,0) = 0, \ x \in \overline{\Omega}. \end{cases}$$

$$\hat{w}(x,\omega) = e^{-\sqrt[4]{-i\omega}(x-x_r)} \mathcal{L}(w(x_r,\cdot))(\omega),$$

then, taking derivative and thanks to continuity

$$\partial_x \hat{w}(x,\omega)|_{x=x_r} = -\sqrt[4]{-i\omega} \hat{w}(x,\omega)|_{x=x_r}$$
$$= -e^{-i\pi/4} \omega \frac{\hat{w}(x,\omega)|_{x=x_r}}{\sqrt{\omega}}$$

## TBCs for linear S. in 1D

#### Inversee Laplace transform

$$\partial_x w(x,t)|_{x=x_r} = -e^{-i\pi/4} \partial_t \left( \frac{1}{\sqrt{\pi}} \int_0^t \frac{w(x,s)|_{x=x_r}}{\sqrt{t-s}} ds \right) = -e^{-i\pi/4} \partial_t^{1/2} w(x_r,t)$$

Similar condition in  $x_l$ 

$$-\partial_x w(x,t)|_{x=x_l} = -e^{-i\pi/4} \partial_t \left( \frac{1}{\sqrt{\pi}} \int_0^t \frac{w(x,s)|_{x=x_l}}{\sqrt{t-s}} ds \right) = -e^{-i\pi/4} \partial_t^{1/2} w(x_l,t)$$

BOUNDARY CONDITION :

$$(\partial_{\mathbf{n}} + e^{-i\pi/4}\partial_t^{1/2})v = 0 \text{ on } \Gamma \times [0, T[.$$

Remark

$$i\partial_t + \partial_x^2 = (\partial_x + \sqrt{-i\partial_t})(\partial_x - \sqrt{-i\partial_t}).$$



### What is known in 1D

LINEAR EQUATIONS WITH TIME DEPENDENT POTENTIALS

•  $\mathscr{V} = 0$  : Dirichlet-to-Neumann map

$$\partial_{\mathbf{n}} u + e^{-i\pi/4} \partial_t^{1/2} u = 0, \quad \text{on } \Sigma_T$$

Tool : Fourier analysis Factorization :  $i\partial_t + \partial_x^2 = \left(\partial_x + i\sqrt{i\partial_t}\right) \left(\partial_x - i\sqrt{i\partial_t}\right)$ 

- Variant :  $\mathscr{V} = V_{l,r}$  constant outside of  $\Omega$
- $\mathscr{V} = V(t)$  : Gauge change

$$v(x,t)=u(x,t)e^{i\mathcal{V}(t)}$$
 with  $\mathcal{V}(t)=\int_0^t V(s)\,ds$ 

v is solution to the free Schrödinger equation. We have access to the exact BC (see above). Therefore, the TBC is for u :

$$\partial_{\mathbf{n}} u + e^{-i\pi/4} \, e^{i\mathcal{V}(t)} \partial_t^{1/2} \left( e^{-i\mathcal{V}(t)} u \right) = 0 \quad \text{on } \Sigma_T$$

## TBCs for linear S. in 1D

SUMMARY : derivation of the analytic TBCs

- To separate the original problem as a system of two coupled equations : interior and exterior problems
- ② To apply the Laplace transform in time t
- 0 To solve the ODE in x
- ${\color{black} \bullet}$  To authorize only the outgoing waves by selecting the decaying solution when  $x \to \pm \infty$
- **(**) To identify the values of Dirichlet and Neumann in  $x_{l,r}$
- Inverse Laplace transform

## EXTENSION TO NLS IN 1D

NONLINEARITIES AND GENERAL REPULSIVE POTENTIALS  $x\partial_x V > 0$  FOR  $x \in \overline{\Omega}$ J. Szeftel (04), X. Antoine - C.B. - S. Descombes (06), X. Antoine - C. B. - P. Klein (09)

 $\mathscr{V} = f(x, u)$ 

• 
$$\mathscr{V} = f(x, u)$$
 and  $\mathcal{V}(x, t) = \int_0^t f(x, u(x, s)) ds$ 

• Absorbing boundary conditions (ABC), tool :  $\Psi$ DO

$$\begin{split} ABC_1^4: \quad \partial_{\mathbf{n}} u + e^{-i\pi/4} e^{i\mathcal{V}} \partial_t^{1/2} \left( e^{-i\mathcal{V}} u \right) - i \frac{\partial_{\mathbf{n}} \mathcal{V}}{4} e^{i\mathcal{V}} I_t \left( e^{-i\mathcal{V}} u \right) = 0 \\ ABC_2^4: \quad \partial_{\mathbf{n}} u - i \sqrt{i\partial_t + \mathcal{V}} u + \frac{1}{4} \partial_{\mathbf{n}} \mathcal{V} (i\partial_t + \mathcal{V})^{-1} u = 0 \end{split}$$

Examples :  $\mathscr{V}=q|u|^2$ ,  $\mathscr{V}=lpha x^2+eta|u|^2$ ,  $lpha\geq 0,\,\ldots$ 





Semi-discrete discretization in time of

Schrödinger Equation in 1D

 $i\partial_t u = -\partial_x^2 u$ ,  $(x,t) \in \mathbb{R}_x \times \mathbb{R}_t^{*+}$ 

A-stable method : time step  $\Delta t$ ,  $u^n$  approx. of  $u(x, n\Delta t)$ .

$$\frac{i}{\Delta t} \sum_{j=0}^{K} \alpha_j u^{n-j} = \sum_{j=0}^{K} \beta_j \left(-\partial_x^2\right) u^{n-j}, \quad n \ge K.$$

Example : Crank-Nicolson K = 1,  $\alpha_0 = 1$ ,  $\alpha_1 = -1$ ,  $\beta_{0,1} = 1/2$ .

$$i\frac{u^{n+1}-u^n}{\Delta t} = -\partial_x^2 \frac{u^{n+1}+u^n}{2}, \quad x \in \mathbb{R}, \forall n \in \mathbb{N}$$

One proceed like for analytic TBCs : splitting in interior and exterior problems.

Instead of Laplace :

 $\mathcal{Z}$ -transform

$$\mathcal{Z}(u^n) = \hat{u}(z) := \sum_{n=0}^\infty u^n \, z^{-n}, \quad z \in \mathbb{C}, \quad |z| > R(\mathcal{Z}(u^n)),$$

where  $R(\mathcal{Z}(u^n))$  is the radius of convergence of the Laurent series.  $\mathcal{Z}(u^n)$ .

Interesting property :

Application of the Z-transform to the numerical scheme with the hypothesis  ${\rm supp}(u^j)\subset [x_l,x_r],\ 0\leq j\leq K-1:$ 

$$\left(\partial_x^2 + i\frac{\delta(z)}{\Delta t}\right)\hat{w}(z) = 0, \quad x > x_r,$$

where

$$\delta(z) = \frac{\sum_{j=0}^{K} \alpha_j z^{K-j}}{\sum_{j=0}^{K} \beta_j z^{K-j}}$$

is the generating function of the time integration scheme.

Examples :

• Crank Nicolson : 
$$\delta(z) = 2 \frac{z-1}{z+1}$$

• Implicit Euler : 
$$\delta(z) = \frac{z-z}{z}$$

Solution of the ODE 
$$\left(\partial_x^2 + i\frac{\delta(z)}{\Delta t}\right)\hat{w}(z) = 0$$
 in  $x$   
 $\hat{w}(x,z) = A^+ e^{i\frac{1}{\sqrt{i\frac{\delta(z)}{\Delta t}}x}} + A^- e^{-i\frac{1}{\sqrt{i\frac{\delta(z)}{\Delta t}}x}}, \quad x > x_r.$ 

One has  $w^n \in L^2(]x_r,\infty[)$ . But, A-stable method  $\Rightarrow \delta$  sends  $\{|z|>1\}$  into  $\{\operatorname{Re}(z)>0\}$ 

$$\operatorname{Re}\left(-i\sqrt[+]{i\frac{\delta(z)}{\Delta t}}\right) > 0 \quad \forall |z| > 1 \quad A^{-} = 0$$

Derivation of  $\hat{w}(x,z)$  w.r.t x

$$\mathcal{Z}(\partial_x w^n)(z) = -e^{-i\pi/4} \sqrt[+]{rac{\delta(z)}{\Delta t}} \mathcal{Z}(w^n)(z),$$

in  $x = x_r$ , then inverse  $\mathcal{Z}$  transform.

Example for Crank-Nicolson (Schmidt-Deuflhard 95, Antoine-Besse 03, ...)

CRANK-NICOLSON

$$i\frac{v^{n+1}-v^n}{\Delta t} = -\partial_x^2 \frac{v^{n+1}+v^n}{2}, \quad x \in \Omega, \forall n \in \mathbb{N}_0, \\ v^0(x) = u^0(x), \quad x \in \Omega, \\ \partial_{\mathbf{n}}v^{n+1} = \sum_{\substack{k=0\\k=0}}^{n+1} \omega_k^{(l,r)}v^{n+1-k}, \quad \text{in } x = x_l, x_r, \\ \omega_k = -e^{-\frac{i\pi}{4}} \frac{2}{\sqrt{2\Delta t}} (-1)^k \tilde{\omega}_k, \quad k \in \mathbb{N}, \\ (\tilde{\omega}_0, \tilde{\omega}_1, \tilde{\omega}_2, \tilde{\omega}_3, \tilde{\omega}_4, \tilde{\omega}_5, \dots) = (1, 1, \frac{1}{2}, \frac{1}{2}, \frac{1 \cdot 3}{2 \cdot 4}, \frac{1 \cdot 3}{2 \cdot 4}, \dots).$$

Consistant quadrature rule with semi-discrete numerical scheme for  $\partial_t^{1/2}$  stability

Othe possibilities :

• Quadrature rule : Mayfield (89), Baskakov & Popov (91)

$$\begin{aligned} \frac{d}{dt} \int_0^t \frac{u(x_r,\tau)}{\sqrt{t-\tau}} \, d\tau \Big|_{t=t_{n+1}} &= \int_0^{t_{n+1}} \frac{u_\tau(x_r,\tau)}{\sqrt{t_{n+1}-\tau}} \, d\tau \\ &\approx \frac{1}{\Delta t} \sum_{k=0}^n (u_J^{k+1} - u_J^k) \int_{t_k}^{t_{k+1}} \frac{d\tau}{\sqrt{t_{n+1}-\tau}}. \end{aligned}$$

Still non local in time

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Still non local in time

• Rational approximation of the symbol Bruneau & DiMenza (95), Szeftel (04) To solve

$$\partial_x \hat{u}(x_r,\tau) = -e^{-i\pi/4} \sqrt[4]{i\tau} \hat{u}(x_r,\tau).$$

Approximation of  $\sqrt[+]{i au}$  by

$$\begin{aligned} & \frac{R_m(i\tau)}{R_m(i\tau)} = a_0^m + \sum_{k=1}^m \frac{a_k^m i\tau}{i\tau + d_k^m} = \sum_{k=0}^m a_k^m - \sum_{k=1}^m \frac{a_k^m d_k^m}{i\tau + d_k^m}, \\ & a_k^m > 0, \quad k \in \{0, \cdots, m\}, \quad d_k^m > 0, \quad k \in \{1, \cdots, m\}. \end{aligned}$$

The equation becomes

$$\partial_x \hat{u}(x_r, \tau) = -e^{i\pi/4} \left[ \left( \sum_{k=0}^m a_k^m \right) \, \hat{u}(x_r, \tau) - \sum_{k=1}^m \frac{a_k^m d_k^m}{i\tau + d_k^m} \, \hat{u}(x_r, \tau) \right].$$

Lindmann trick (85); auxiliary functions  $\varphi_k=\varphi_k(t)_{k=1,\cdots,m}$  which satisfy

$$\frac{1}{i\tau + d_k^m} \hat{u}(x_r) = \hat{\varphi}_k, \quad k = 1, \cdots, m.$$

Inverse Laplace transform : ODE for  $\varphi_k$ 

$$i\frac{d\varphi_k}{dt} + d_k^m\varphi_k = u(x_r, t), \quad \varphi_k(0) = 0, \quad k = 1, \cdots, m.$$

so, the BC is

$$\begin{cases} \partial_{\mathbf{n}} u = -e^{-\frac{i\pi}{4}} \left[ \left( \sum_{k=0}^{m} a_{k}^{m} \right) u - \sum_{k=1}^{m} a_{k}^{m} d_{k}^{m} \varphi_{k} \right], & \text{in } x = x_{r}, \ t > 0, \\ i \frac{d\varphi_{k}}{dt} + d_{k}^{m} \varphi_{k} = u(x_{r}, t), & t > 0, k = 1, \cdots, m, \\ \varphi_{k}(0) = 0, & t > 0, k = 1, \cdots, m. \end{cases}$$

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# INTRODUCTION

# **2** One dimensional Schrödinger Eq.

# Two dimensional Schrödinger Eq. with potential

## **(1)** Extension to 2D nonlinear equation



• Straight boundary : extension of the 1D study

Domain 
$$\Omega = \{x < 0\}$$
  
 $i\partial_t + \partial_y^2$  plays the part of  $i\partial_t$  in 1D  
 $\partial_x^2$  plays the part of  $\partial_x^2$   
TBC :  $\partial_{\mathbf{n}} u - i\sqrt{i\partial_t + \partial_y^2} u = 0.$ 



• FACTORIZATION :

$$i\partial_t + \Delta = i\partial_t + \partial_y^2 + \partial_x^2 = \left(\partial_x + i\sqrt{i\partial_t + \partial_y^2}\right) \left(\partial_x - i\sqrt{i\partial_t + \partial_y^2}\right) + R$$

• Problems :

Junction problems located on the corners Nonlocal operator both in time and space



### Geometrical aspect : consequences

• TAKE INTO ACCOUNT THE GEOMETRY : convex set with general boundary, smooth, with curvature  $\kappa$ .



• GENERALIZED COORDINATES SYSTEM of the boundary with respect to normal variable r and curvilinear abscissa s

$$\Delta = \partial_r^2 + \kappa_r \partial_r + h^{-1} \partial_s \left( h^{-1} \partial_s \right)$$

 $\kappa_r = h^{-1}\kappa$  : curvature of a parallel surface  $\Sigma_r$  to  $\Sigma$   $h(r,s) = 1 + r\kappa$ 

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 $\Rightarrow \quad L = \partial_r^2 + \kappa_r \partial_r + i\partial_t + h^{-1} \partial_s \left( h^{-1} \partial_s \right) + V$ 

Schrödinger equation with variable coefficients : pseudo-differential calculus

 $t \longleftrightarrow t$  dual variable  $\tau$  $x \longleftrightarrow r$  $y \longleftrightarrow s$  dual variable  $\xi$ 



### Two strategies

## STRATEGY 1 : GAUGE CHANGE

• Change of unknown (which solves the case  $\mathscr{V} = V(t)$ )

$$v=e^{-i\mathcal{V}}u \quad ext{with} \quad \mathcal{V}(r,s,t)=\int_0^t V(r,s,\sigma)\,d\sigma$$

 $\bullet\,$  We work on the equation with unknown v :

$$i\partial_t v + \partial_r^2 v + (\kappa_r + F)\partial_r v + h^{-1}\partial_s (h^{-1}\partial_s v) + G v = 0$$

### STRATEGY 2 : DIRECT METHOD

• Equation sets in generalized coordinates

$$i\partial_t u + \partial_r^2 u + \kappa_r \partial_r u + h^{-1} \partial_s (h^{-1} \partial_s u) + V u = 0$$

GENERALIZED SCHRÖDINGER EQUATION

$$i\partial_t w + \partial_r^2 w + (\kappa_r + A)\partial_r w + h^{-1}\partial_s (h^{-1}\partial_s w) + Bw = 0$$

S1 
$$A = F(r, s, t)$$
 and  $B = G(r, s, t)$  if  $w = v = e^{-i\mathcal{V}}u$   
S2  $A = 0$  and  $B = V(r, s, t)$  if  $w = u$ 

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#### VARIABLE COEFFICIENTS SCHRÖDINGER EQUATION

 $Lw := i\partial_t w + \partial_r^2 w + (\kappa_r + A)\partial_r w + h^{-1}\partial_s (h^{-1}\partial_s w) + Bw = 0.$ 

- Factorization of L in a neighbourhood of  $\Sigma$
- Use of  $\Psi DO$  calculus instead of Fourier
- Symbolic calculus : asymptotic expansion of symbols
- Select outgoing waves : identification of principal symbol
- $\bullet\,$  Come back to the surface  $\Sigma\,$
- DtN operator non local both in space and time : localization techniques
  - Taylor approach
  - Padé approach

#### PSEUDODIFFERENTIAL OPERATORS

•  $P(r, s, t, \partial_s, \partial_t)$  defined by its total symbol  $p(r, s, t, \xi, \tau)$  in Fourier space by  $\mathscr{F}_{(s,t)}$  ( $\xi$  and  $\tau$  dual variables of s and t)

$$P(r, s, t, \partial_s, \partial_t)u(r, s, t) = \int_{\mathbb{R} \times \mathbb{R}} p(r, s, t, \xi, \tau) \hat{u}(r, \xi, \tau) e^{is\xi} e^{it\tau} d\xi d\tau$$

Notations : P = Op(p) ,  $p = \sigma(P)$ 

• E = (1, 2). f is said *E-quasi homogeneous* of order m if

$$f(r, s, t, \mu\xi, \mu^2\tau) = \mu^m f(r, s, t, \xi, \tau)$$

Example :  $\sqrt{-\tau - \xi^2}$  is E-quasi homogeneous of order 1.

•  $p \in S^m_E$  (or  $P \in OPS^m_E$ ) if it admits an asymptotic expansion in E-quasi homogeneous symbols

$$p(r,s,t,\xi,\tau) \sim \sum_{j=0}^{+\infty} p_{m-j}(r,s,t,\xi,\tau),$$

which means

$$\left(p(r,s,t,\xi,\tau) - \sum_{j=0}^{\tilde{m}} p_{m-j}(r,s,t,\xi,\tau)\right) \in S_E^{m-(\tilde{m}+1)}, \quad \forall \tilde{m} \in \mathbb{N}.$$

•  $p = q \mod S_E^m$  means  $p - q \in S_E^m$ . • Composition rule :  $\sigma(AB) \sim \sum_{|\alpha|=0}^{+\infty} \frac{(-i)^{|\alpha|}}{\alpha!} \partial^{\alpha}_{(\xi,\tau)} \sigma(A) \partial^{\alpha}_{(s,t)} \sigma(B)$ 

## VARIABLE COEFFICIENTS SCHRÖDINGER EQUATION

$$i\partial_t w + \partial_r^2 w + (\kappa_r + A)\partial_r w + h^{-1}\partial_s (h^{-1}\partial_s w) + Bw = 0.$$

Engquist & Majda method.

There exist two  $\Psi {\rm DO}~\Lambda^-$  and  $\Lambda^+$  of  ${\rm OPS}^1_E$  s.t. we get the following Nirenberg-like factorization

 $i\partial_t + \partial_r^2 + (\kappa_r + A)\partial_r + h^{-1}\partial_s(h^{-1}\partial_s) + B = (\partial_r + i\Lambda^-)(\partial_r + i\Lambda^+) + R$ 

where R is a smoothing operator of  $OPS_E^{-\infty}$ .

 $\Lambda^+$  (resp.  $\Lambda^-$ ) has an asymptotic expansion in E-quasi homogeneous symbols :

$$\sigma(\Lambda^{+}) = \lambda^{+} \sim \sum_{j=0}^{+\infty} \lambda_{1-j}^{+} = \lambda_{1}^{+} + \lambda_{0}^{+} + \lambda_{-1}^{+} + \lambda_{-2}^{+} + \dots$$

with  $\lambda_{1-j}^+ \in S_E^{1-j}$ . Come back to the surface  $\Sigma$ :  $\widetilde{\Lambda^+} = \Lambda_{|r=0}^+$  and  $\widetilde{\lambda_j} = (\lambda_j^+)_{|r=0}$ .

 $\operatorname{TBC}: \ \partial_{\mathbf{n}} w + i \, \widetilde{\Lambda^+} w = 0$ 

$$\partial_{\mathbf{n}} w + i \sum_{j=0}^{+\infty} Op\left(\widetilde{\lambda_{1-j}}\right) w = 0 \ , \quad \text{on } \Sigma_T.$$

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## DERIVATION OF THE ABCS

APPROXIMATED CONDITION OF ORDER M: we only keep the first M terms

$$\partial_{\mathbf{n}} w_M + i \sum_{j=0}^M Op\left(\widetilde{\lambda}_{1-j}\right) w_M = 0 \;, \quad \text{on } \Sigma_T$$

•  $\lambda_{1-j}^+$ ,  $j \ge 0$ , depends on  $\lambda_1^+$ .

• Identification of the principal symbol  $\lambda_1^+$  :

Outgoing wave  $\operatorname{Im}(\lambda_1^+(s,t,\xi,\tau)) \leq 0$ , for  $|\tau| \gg 1$ 

Strategy 1  $\lambda_1^+ = -\sqrt{-\tau - h^{-2}\xi^2}$ 

Strategy 2  $\lambda_1^+ = -\sqrt{-\tau - h^{-2}\xi^2 + V}$ 

Asymptotic expansion :  $\tilde{\lambda}_j$  are functions of parameter  $\sqrt{-\tau - \xi^2}$  (resp.  $\sqrt{-\tau - \xi^2 + V}$ ).

 $\implies$  non local operators both in time AND in space

#### LOCALIZING IN SPACE : TWO APPROACHES

Two approaches, valid for both strategies :

• "TAYLOR" APPROACH : Taylor expansion of the symbols for  $| au| \gg \xi^2$ 

$$-\tau - \xi^2 + V = -\tau \left(1 + \frac{\xi^2}{\tau} - \frac{V}{\tau}\right)$$

Thereby :

$$\sqrt{-\tau-\xi^2+V}\approx \sqrt{-\tau}\left(1+\frac{\xi^2}{2\tau}-\frac{V}{2\tau}\right)=\sqrt{-\tau}-\frac{\xi^2}{2}\frac{1}{\sqrt{-\tau}}+\frac{V}{2}\frac{1}{\sqrt{-\tau}}$$

 $\implies$  Localizing in space only

• Padé approximation approach :

$$Op\left(\sqrt{-\tau-\xi^2+V}\right)\sim \sqrt{i\partial_t+\Delta_{\Sigma}+V} \mod OPS^{-1}$$

formal approximation of  $\sqrt{\cdot}$  by Padé approximants  $\Longrightarrow$  Localizing both in space AND time

Two possible approaches for each strategy, so 4 families of ABC.

	"Taylor" approach	" Padé" approach
Gauge change	$ABC^M_{1,T}$	$ABC^M_{1,P}$
Direct method	$ABC_{2,T}^M$	$ABC_{2,P}^M$

 $\downarrow \qquad \qquad \downarrow \\ \partial_t^{1/2}, I_t^{1/2}, I_t \qquad Op\left(\sqrt{-\tau - \xi^2}\right)$ 

or

 $v = e^{-i\mathcal{V}}u$   $Op\left(\sqrt{-\tau - \xi^2 + V}\right)$ 

#### • Gauge change

 $\begin{aligned} \mathsf{ABC}_{1,T}^2 & \partial_{\mathbf{n}} u + e^{-i\pi/4} e^{i\mathcal{V}} \partial_t^{1/2} \left( e^{-i\mathcal{V}} u \right) + \frac{\kappa}{2} u \\ \mathsf{ABC}_{1,T}^3 & - e^{i\pi/4} e^{i\mathcal{V}} \left( \frac{\kappa^2}{8} + \frac{\Delta_{\Sigma}}{2} + i\partial_s \mathcal{V} \partial_s + \frac{1}{2} (i\partial_s^2 \mathcal{V} - (\partial_s \mathcal{V})^2) \right) I_t^{1/2} \left( e^{-i\mathcal{V}} u \right) \\ \mathsf{ABC}_{1,T}^4 & + i e^{i\mathcal{V}} \left( \frac{\partial_s (\kappa \partial_s)}{2} + \frac{\kappa^3 + \partial_s^2 \kappa}{8} + \frac{i\partial_s \kappa \partial_s \mathcal{V}}{2} \right) I_t \left( e^{-i\mathcal{V}} u \right) \\ & - i \frac{\mathrm{sg}(\partial_{\mathbf{n}} \mathcal{V})}{4} \sqrt{|\partial_{\mathbf{n}} \mathcal{V}|} e^{i\mathcal{V}} I_t \left( \sqrt{|\partial_{\mathbf{n}} \mathcal{V}|} e^{-i\mathcal{V}} u \right) = 0 \end{aligned}$ 

#### • Direct method

$$\begin{split} \mathsf{ABC}_{2,T}^2 & \partial_{\mathbf{n}} u + e^{-i\pi/4} \partial_t^{1/2} u + \frac{\kappa}{2} u \\ \mathsf{ABC}_{2,T}^3 & - e^{i\pi/4} \left(\frac{\kappa^2}{8} + \frac{\Delta \Sigma}{2}\right) I_t^{1/2} u - e^{i\pi/4} \frac{\operatorname{sg}(V)}{2} \sqrt{|V|} I_t^{1/2} \left(\sqrt{|V|} u\right) \\ \mathsf{ABC}_{2,T}^4 & + i \left(\frac{\partial_s(\kappa \partial_s)}{2} + \frac{\kappa^3 + \partial_s^2 \kappa}{8}\right) I_t u - i \frac{\operatorname{sg}(\partial_{\mathbf{n}} V)}{4} \sqrt{|\partial_{\mathbf{n}} V|} I_t \left(\sqrt{|\partial_{\mathbf{n}} V|} u\right) = 0 \end{split}$$

## ABC : PADÉ APPROACH

### • GAUGE CHANGE

$$\begin{aligned} \mathsf{ABC}_{1,P}^{1} & \partial_{\mathbf{n}} u - i e^{i \mathcal{V}} \sqrt{i \partial_{t} + \Delta_{\Sigma}} \left( e^{-i \mathcal{V}} u \right) \\ \mathsf{ABC}_{1,P}^{2} & + \frac{\kappa}{2} u + \partial_{s} \mathcal{V} e^{i \mathcal{V}} \partial_{s} \left( i \partial_{t} + \Delta_{\Sigma} \right)^{-1/2} \left( e^{-i \mathcal{V}} u \right) \\ & - \frac{\kappa}{2} e^{i \mathcal{V}} (i \partial_{t} + \Delta_{\Sigma})^{-1} \Delta_{\Sigma} \left( e^{-i \mathcal{V}} u \right) = 0 \end{aligned}$$

### • Direct method

$$\begin{aligned} \mathsf{ABC}_{2,P}^{1} & \partial_{\mathbf{n}} u - i\sqrt{i\partial_{t} + \Delta_{\Sigma} + V u} \\ \mathsf{ABC}_{2,P}^{2} & + \frac{\kappa}{2}u - \frac{\kappa}{2}\left(i\partial_{t} + \Delta_{\Sigma} + V\right)^{-1}\Delta_{\Sigma} u = 0 \end{aligned}$$

#### Semi-discretization and implementation

#### INTERIOR PROBLEM :

Semi-discret Crank-Nicolson scheme, symmetrical, unconditionally stable

$$\frac{2i}{\Delta t}u^{n+1/2} + \Delta u^{n+1/2} + V^{n+1/2}u^{n+1/2} = \frac{2i}{\Delta t}u^n$$

#### ABC DISCRETIZATION

- Taylor approach : approximation of the operators  $\partial_t^{1/2}, \ I_t^{1/2}$  and  $I_t$  by quadrature formulas
- $\bullet$  Padé approach : coupled system between  $u^{n+1/2}$  and the m auxiliary functions  $\varphi_k^{n+1/2}$ 
  - Rational approximation of the square root by Padé approximants

$$\sqrt{z} \approx R_m(z) = \sum_{k=0}^m a_k^m - \sum_{k=1}^m \frac{a_k^m d_k^m}{z + d_k^m}$$

• In the  $ABC^{M}_{2,P}$  conditions :

$$\sqrt{i\partial_t + \Delta_{\Sigma} + V} \quad \underset{R_m}{\sim} \quad R_m \left( i\partial_t + \Delta_{\Sigma} + V \right)$$

$$\Rightarrow \sqrt{i\partial_t + \Delta_{\Sigma} + V}u \approx \left(\sum_{k=0}^m a_k^m\right)u - \sum_{k=1}^m a_k^m d_k^m \underbrace{(i\partial_t + \Delta_{\Sigma} + V + d_k^m)^{-1}u}_{\varphi_k}$$

Auxiliary functions  $\varphi_k$ , solutions of a Schrödinger equation on  $\Sigma_T$ .

## NUMERICAL EXAMPLES

 $V(r) = 5r^2$ 

Domain : disk of radius 5 Initial datum :  $u_0(x,y)=e^{-(x^2+y^2)-ik_0x}$  , with  $k_0=10$   $\Delta t=10^{-3},\ T=1$ 

 $Mesh: 1\,700\,000$  triangles

Movie

25 Padé functions

Logarithmic levels bounded at  $10^{-4}$ 



POTENTIAL



SOLUTION

 $V(r) = 5r^2$ 

#### GAUGE CHANGE

#### DIRECT METHOD





Padé approach

# V(r) = 5r plectrum case

 $\Delta t = 2 \times 10^{-3}$ 920 000 triangles



Computational domain



0.4

GAUGE CHANGE

#### Direct method



 $ABC_{2,T}^4$ 





Potential profile



# $V(r,t) = 5r^2 \left(1 + \cos(4\pi t)\right)$

 $\Delta t = 10^{-3} \\ 1\,700\,000 \text{ triangles}$ 



GAUGE CHANGE

Direct method

# **INTRODUCTION**

**2** One dimensional Schrödinger Eq.

## **3** Two dimensional Schrödinger Eq. with potential

## EXTENSION TO 2D NONLINEAR EQUATION



POTENTIAL  $\mathscr{V} = V + f(u)$ 

- For  $k_0 \neq 0$ , u is never radially symetrical  $\Rightarrow \mathcal{V}$  is never radially symetrical
- Make the implementation of ABC linked to Gauge change more complexe + numerical cost

$$\rightarrow$$
 limitation to  $NLABC_{1,T}^2$  ( $M = 2$  only)

- ightarrow Do not use  $NLABC^M_{1,P}$  (identical precision as  $NLABC^M_{1,T}$  for a potential)
  - $\bullet$  We deal with  $NLABC_{1,T}^2,~NLABC_{2,T}^M,$  and  $NLABC_{2,P}^M$
  - FORMAL SUBSTITUTIONS  $\mathscr{V} = V + f(u)$  AND  $\mathcal{V}(x, y, t) = \int_{0}^{t} V + \int_{0}^{t} f(u)$
  - We derive the boundary conditions  $NLABC_{1,T}^2$ ,  $NLABC_{2,T}^3$  and  $NLABC_{2,P}^2$ .

• TAYLOR APPROACH, GAUGE CHANGE

$$NLABC_{1,T}^2 \qquad \partial_{\mathbf{n}} u + e^{-i\pi/4} e^{i\mathcal{V}} \partial_t^{1/2} \left( e^{-i\mathcal{V}} u \right) + \frac{\kappa}{2} u = 0$$

• TAYLOR APPROACH, DIRECT METHOD

$$\begin{split} NLABC_{2,T}^2 & \partial_{\mathbf{n}} u + e^{-i\pi/4} \partial_t^{1/2} u + \frac{\kappa}{2} u \\ NLABC_{2,T}^3 & - e^{i\pi/4} \left( \frac{\kappa^2}{8} + \frac{\Delta\Sigma}{2} \right) I_t^{1/2} u - e^{i\pi/4} \frac{\operatorname{sg}(f(u))}{2} \sqrt{|f(u)|} I_t^{1/2} \left( \sqrt{|f(u)|} u \right) \\ NLABC_{2,T}^4 & + i \left( \frac{\partial_s(\kappa \partial_s)}{2} + \frac{\kappa^3 + \partial_s^2 \kappa}{8} \right) I_t u \\ & -i \frac{\operatorname{sg}(\partial_{\mathbf{n}} f(u))}{4} \sqrt{|\partial_{\mathbf{n}} f(u)|} I_t \left( \sqrt{|\partial_{\mathbf{n}} f(u)|} u \right) = 0 \end{split}$$

• Padé Approach, direct method

 $NLABC_{2,P}^{1} \qquad \partial_{\mathbf{n}} u - i\sqrt{i\partial_{t} + \Delta_{\Sigma} + f(u)} u$  $NLABC_{2,P}^{2} \qquad \qquad + \frac{\kappa}{2}u - \frac{\kappa}{2} (i\partial_{t} + \Delta_{\Sigma} + f(u))^{-1} \Delta_{\Sigma} u = 0$ 

• INTERIOR PROBLEM Duràn - Sanz-Serna scheme

$$i\frac{u^{n+1} - u^n}{\Delta t} + \Delta \ \frac{u^{n+1} + u^n}{2} + f\left(\frac{u^{n+1} + u^n}{2}\right) \frac{u^{n+1} + u^n}{2} = 0$$

• BOUNDARY CONDITION : discrte convolutions and Padé approximants

#### SOLUTION TO THE NONLINEAR EQUATION

• Fixed point scheme : Mass inequality valid  $\|u^n\|_{L^2(\Omega)} \le \|u^0\|_{L^2(\Omega)}$ 

- $\bullet~ {\rm for}~ {\rm NLABC}^2_{2,T}$  and  ${\rm NLABC}^2_{1,T}$
- for  $\mathsf{NLABC}_{2,T}^3$  if  $V \ge 0$  and  $f(u) \ge 0$ .
- Numerical alternative scheme : relaxation method [CB 04] .

• Principle : Solution of the equation  $i\partial_t u + \Delta u + f(u)u = 0$  solving the system

$$\begin{cases} i\partial_t u + \Delta u + \Upsilon u = 0, & \text{on } \Omega_T, \\ \Upsilon = f(u), & \text{on } \Omega_T. \end{cases}$$

• Semi-discretization

$$\begin{cases} i\frac{u^{n+1}-u^n}{\Delta t} + \Delta u^{n+1/2} + \Upsilon^{n+1/2}u^{n+1/2} = 0, \\ \frac{\Upsilon^{n+3/2} + \Upsilon^{n+1/2}}{2} = f(u^{n+1}), \end{cases} \text{ for } 0 \le n \le N$$

où 
$$\Upsilon^{n+1/2}=rac{\Upsilon^{n+1}+\Upsilon^n}{2},\ \Upsilon^{-1/2}=f(u^0).$$

 ADVANTAGES : Conservation of the invariants (mass, energy), simplicity, speed (no fixed point iteration) • Cubic equation  $i\partial_t + \Delta u + q|u|^2 = 0$ 

• Numerical fabrication of the soliton : stationary solutions computation leads to

$$\begin{cases} \partial_r^2 \psi + \frac{1}{r} \partial_r \psi - \psi + q |\psi|^2 \psi = 0, \quad 0 < r < R, \\ \psi'(0) = 0, \quad \psi(0) = \beta, \end{cases}$$

solved by a shooting method [Di Menza 09]



#### WITHOUT POTENTIAL



 $ABC_{0,T}^3$ 



 $ABC_{0,P}^2$ 

#### GAUGE CHANGE



 $\mathrm{NLABC}_{1,T}^2$ 

Initial datum : soliton Domain : disk of radius 10  $\Delta t = 2 \times 10^{-3}$  $1\,700\,000$  triangles  $k_0 = 5$ T = 2Movie Movie contour

#### Direct method



 $NLABC_{2,T}^3$ 



 $NLABC_{2,P}^2$ 



 $ABC_{0,T}^3$ 



 $ABC_{0,P}^2$ 

GAUGE CHANGE



 $\mathrm{NLABC}_{1,T}^2$ 

DIRECT METHOD



 $\mathrm{NLABC}_{2,T}^3$ 



 $\mathrm{NLABC}_{2,P}^2$